



Algorithms: Design
and Analysis, Part II

Advanced Union-Find

Tarjan's Analysis

Tarjan's Bound

Theorem: [Tarjan 75] With Union by Rank and path compression, m UNION+FIND operations take $O(m\alpha(n))$ time, where $\alpha(n)$ is the inverse Ackerman function

Acknowledgement: Kozen, "Design and Analysis of Algorithms"

Building Blocks of Hopcroft-Ullman Analysis

Block #1: Rank Lemma (at most $n/2^r$ objects of rank r)

Block #2: Path compression \Rightarrow If x 's parent pointer updated from p to p' , then $\text{rank}(p') \geq \text{rank}(p) + 1$

New idea: Stronger version of building block #2. In most cases, rank of new parent much bigger than rank of old parent (not just by 1).

Quantifying Rank Gaps

Definition: Consider a non-root object x (so $\text{rank}[x]$ fixed forevermore)

Define $\delta(x) = \max$ value of k such that $\text{rank}[\text{parent}[x]] \geq A_k(\text{rank}[x])$

(Note $\delta(x)$ only goes up over time)

Examples: Always have $\delta(x) \geq 0$

$$\delta(x) \geq 1 \iff \text{rank}[\text{parent}[x]] \geq 2 \text{ rank}[x]$$

$$\delta(x) \geq 2 \iff \text{rank}[\text{parent}[x]] \geq \text{rank}[x] 2^{\text{rank}[x]}$$

Note: For all objects x with $\text{rank}[x] \geq 2$, then $\delta(x) \leq \alpha(n)$
[Since $A_{\alpha(n)}(2) \geq n$]

Good and Bad Objects

Definition: An object x is bad if all of the following hold:

- (1) x is not a root
- (2) $\text{parent}(x)$ is not a root
- (3) $\text{rank}(x) \geq 2$
- (4) x has an ancestor y with $\delta(y) = \delta(x)$

x is good otherwise.

Quiz

Question: What is the maximum number of good objects on an object-root path?

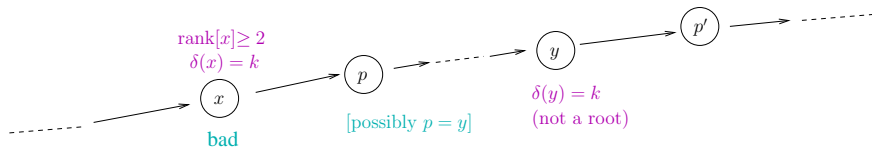
- A) $\Theta(1)$
- B) $\Theta(\alpha(n))$
- C) $\Theta(\log^* n)$
- D) $\Theta(\log n)$

\leq 1 root + 1 child of root
+ 1 object with rank 0
+ 1 object with rank 1
+ 1 object with $\delta(x) = k$
for each $k = 0, 1, 2, \dots, \alpha(n)$

Proof of Tarjan's Bound

Upshot: Total work of m operations = $O(m\alpha(n))$ (visits to good objects) + total # of visits to bad objects (will show is $O(n\alpha(n))$)

Main argument: Suppose a FIND operation visits a bad object x :



Path compression: x 's new parent will be p' or even higher.

$$\Rightarrow \text{rank}[x\text{'s new parent}] \geq \text{rank}[p'] \geq A_k(\text{rank}[y]) \geq A_k(\text{rank}[p])$$

ranks only go up

since $\delta(y) = k$

ranks only go up

Proof of Tarjan's Bound II

Point: Path compression (at least) applies the A_k function to $\text{rank}[x\text{'s parent}]$

Consequence: If $r = \text{rank}[x]$ (≥ 2), then after r such pointer updates we have

$$\text{rank}[x\text{'s parent}] \geq (A_k \circ \dots \text{ } r \text{ times } \dots \circ A_k)(r) = A_{k+1}(r)$$

Definition of Ackermann function

Thus: While x is bad, every r visits increases $\delta(x)$
 $\Rightarrow \leq r\alpha(n)$ visits to x while it's bad

Proof of Tarjan's Bound III

Recall: Total work of m operations is $O(m\alpha(n))$ (visits to good objects) + total # of visits to bad objects.

$$\leq \sum_{\text{objects } x} \text{rank}[x] \alpha(n)$$

$$= \alpha(n) \sum_{r \geq 0} r \cdot (\# \text{ of objects with rank } r)$$

$\leq n/2^r$ for each r by the Rank Lemma

$$= n\alpha(n) \sum_{r \geq 0} r/2^r \longrightarrow = O(1)$$

$$= O(n\alpha(n)). \quad \text{QED!}$$

Epilogue

“This is probably the first and maybe the only existing example of a simple algorithm with a very complicated running time. . . . I conjecture that there is no linear-time method, and that the algorithm considered here is optimal to within a constant factor.”

-Tarjan, “Efficiency of a Good But Non Linear Set Union Algorithm”, Journal of the ACM, 1975.

Conjecture proved by [Fredman/Saks 89]!